

1 Analysis of Algorithms

The **running time** of a program can be modeled by the number of instructions executed by the computer. To simplify things, suppose arithmetic operators (+, -, *, /), logical operators (&&, ||, !), comparison (==, <, >), assignment, field access, array indexing, and so forth take 1 unit of time. (6 + 3 * 8) / 3 would take 3 units of time, one for each arithmetic operator.

While this measure is fine for simple operations, many problems in computer science depend on the size of the input: `fib(3)` executes almost instantly, but `fib(10000)` will take much longer to compute.

Asymptotic analysis is a method of describing the run-time of an algorithm *with respect* to the size of its input. We can now say,

The run-time of `fib` is, at most, within a factor of 2^N where N is the size of the input number.

Or, in formal notation, $\text{fib}(n) \in O(2^N)$.

1.1 Define, in your own words, each of the following asymptotic notation.

(a) O

(b) Ω

(c) Θ

1.2 Give a tight asymptotic runtime bound for `containsZero` as a function of N , the size of the input array in the *best case*, *worst case*, and *overall*.

```
public static boolean containsZero(int[] array) {
    for (int value : array) {
        if (value == 0) {
            return true;
        }
    }
    return false;
}
```

2 Something Fishy

Give a tight asymptotic runtime bound for each of the following functions. Assume array is an $M \times N$ matrix (*rows* \times *cols*) and that M and N are both large.

```
2.1 public static int redHerring(int[][] array) {
    if (array.length < 1 || array[0].length <= 4) {
        return 0;
    }
    for (int i = 0; i < array.length; i++) {
        for (int j = 0; j < array[i].length; j++) {
            if (j == 4) {
                return -1;
            }
        }
    }
    return 1;
}

2.2 public static int crimsonTuna(int[][] array) {
    if (array.length < 4) {
        return 0;
    }
    for (int i = 0; i < array.length; i++) {
        for (int j = 0; j < array[i].length; j++) {
            if (i == 4) {
                return -1;
            }
        }
    }
    return 1;
}
```

```
2.3 public static int pinkTrout(int a) {  
    if (a % 7 == 0) {  
        return 1;  
    } else {  
        return pinkTrout(a - 1) + 1;  
    }  
}
```

2.4 (a) Give a $O(\cdot)$ runtime bound as a function of N , `sortedArray.length`.

```
private static boolean scarletKoi(int[] sortedArray, int x, int start, int end) {  
    if (start == end || start == end - 1) {  
        return sortedArray[start] == x;  
    }  
    int mid = end + ((start - end) / 2);  
    return sortedArray[mid] == x ||  
        scarletKoi(sortedArray, x, start, mid) ||  
        scarletKoi(sortedArray, x, mid, end);  
}
```

(b) Why can we only give a $O(\cdot)$ runtime and not a $\Theta(\cdot)$ runtime?

3 Shoutout Recursion

- 3.1 Give a tight asymptotic bound for `many_N` as a function of N and M . If possible, give a $\Theta(\cdot)$ bound for the overall runtime. Otherwise, provide a $\Theta(\cdot)$ bound for both the best case and worst case runtime.

```

int many_N(int N, int M) {
    if (N == 0) { return 1;}
    int k = 0;
    for (int i = 0; i <= M; i++) {
        k += many_N(N-1, M)
    }
    return k;
}

```

- 3.2 Give a tight asymptotic bound for `skip` as a function of N . If possible, give a $\Theta(\cdot)$ bound for the overall runtime. Otherwise, provide a $\Theta(\cdot)$ bound for both the best case and worst case runtime.

```

void skip(int N) {
    if (N <= 1) { return;}
    else {
        skip(N/N);
        skip(N/2);
    }
}

```

4 Disjoint Sets Intro

- 4.1 Suppose we have a `WeightedQuickUnionUF` disjoint set with path compression. Show the tree structure in the union-find algorithm as the following sequence of commands is executed.

```
connect(1, 2);
```

```
connect(3, 4);
```

```
connect(5, 6);
```

```
connect(1, 6);
```

```
connect(3, 6);
```